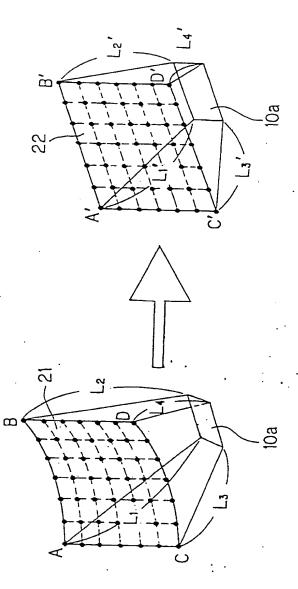
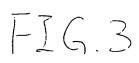


- 3: interface
- 10: CCD camera
- 11: distance measurement unit
- 12: scanner
- 13: controller
- 14: signal processor
- 15: image memory
- 16: synthesization controller





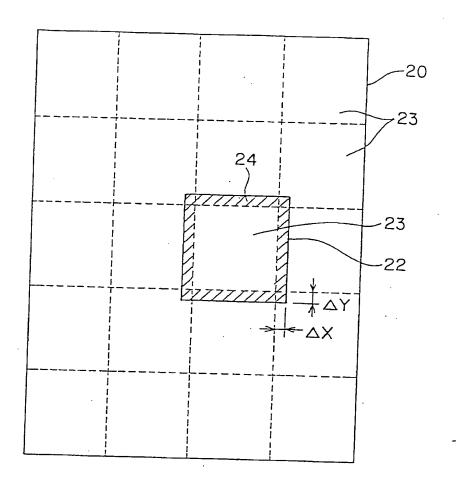
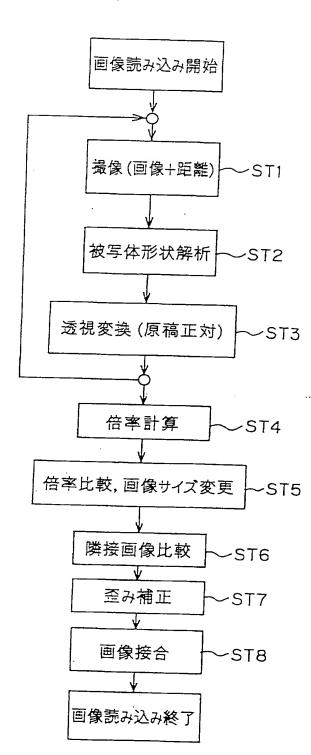


FIG. 4



Start image reading

ST1: Acquire image (image + distance).

ST2: Analyze shape of object.

ST3: Perspective transformation (positive document pair)

ST4: Calculate magnification rates.

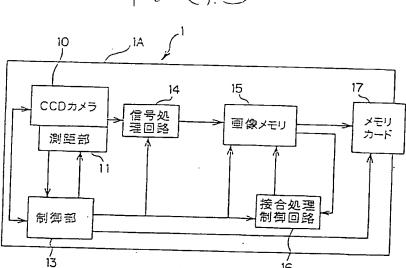
ST5: Compare magnification rates and change image sizes.

ST6: Compare adjacent images.

ST7: Correct distortion.

ST8: Synthesize images.

End image reading



10: CCD camera

distance measurement unit

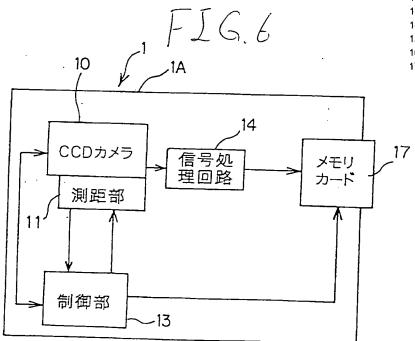
controller

signal processor

image memory

synthesization controller

17: memory card



16

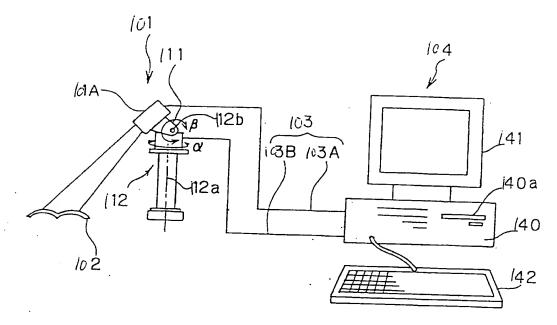
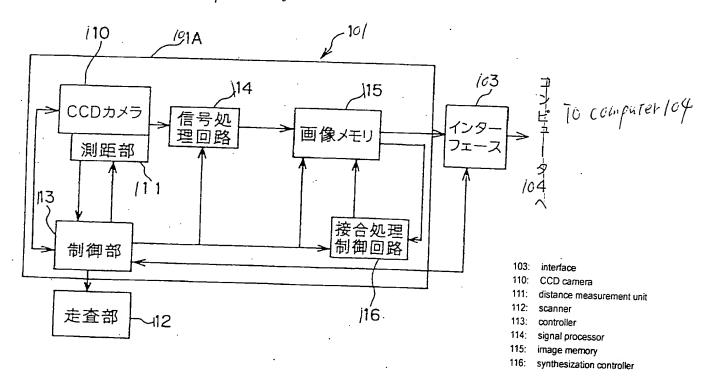
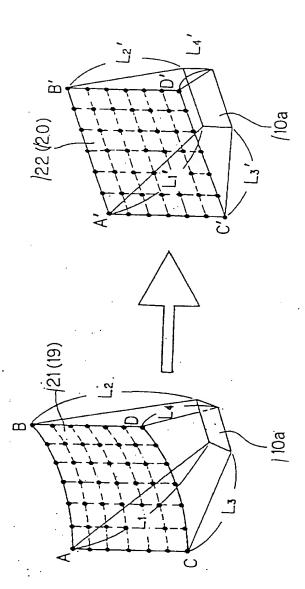
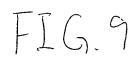
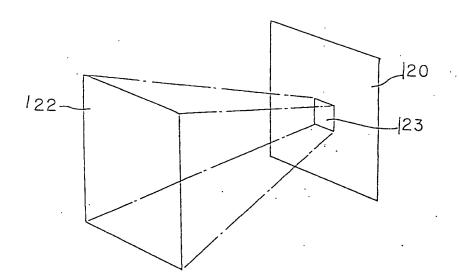


FIG. 1B







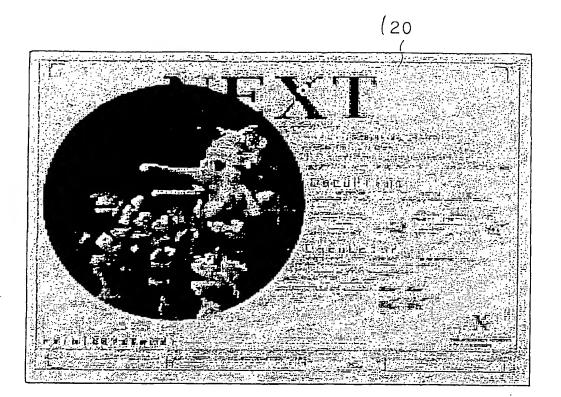


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FIG. 10A



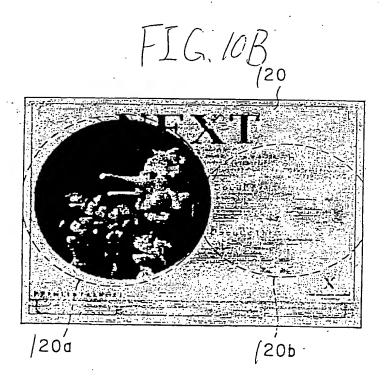


FIG. //A

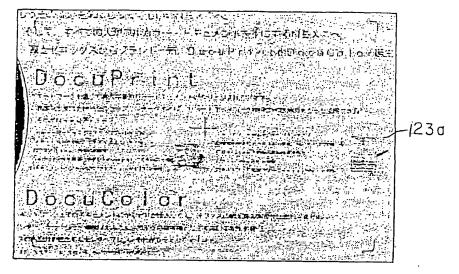


FIG. 11B

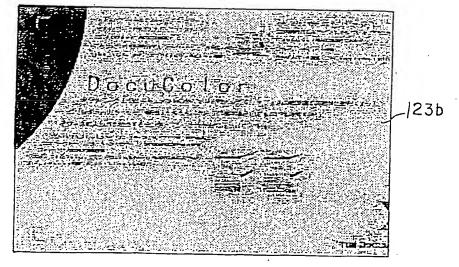


FIG. 11C

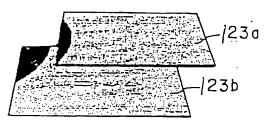


FIG. 12A



FIG. 12B

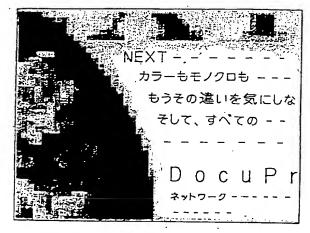
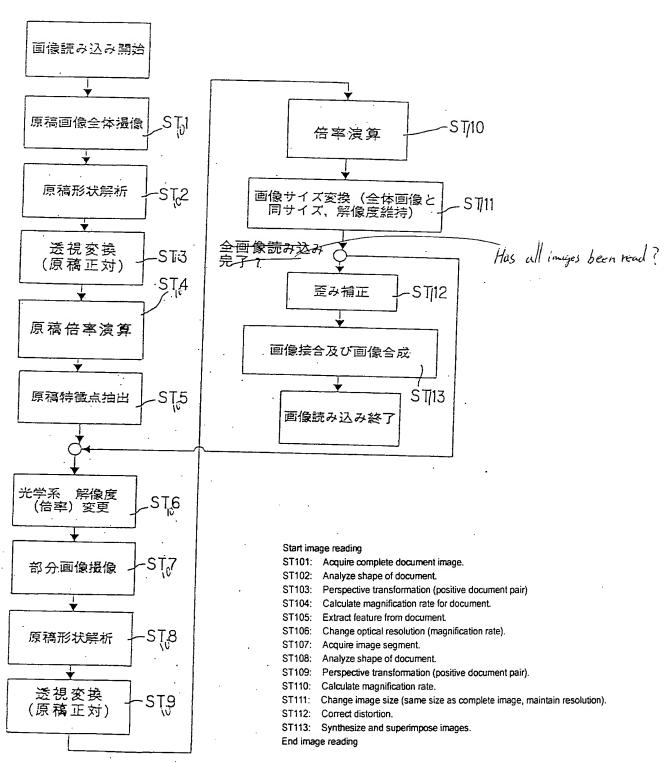
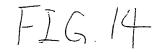
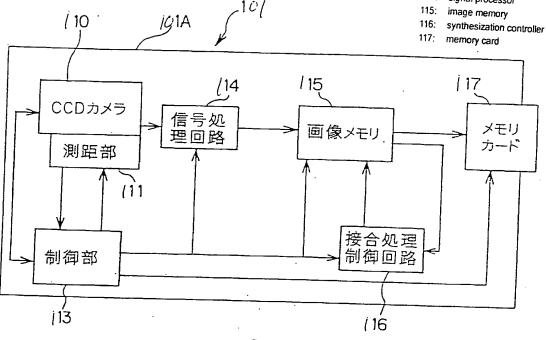


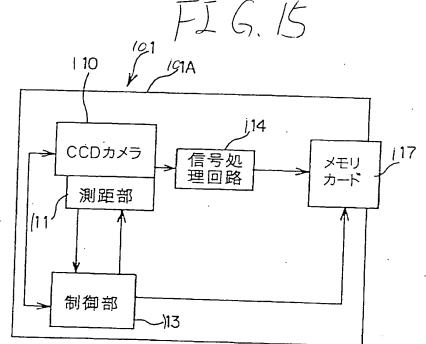
FIG. B





- 110: CCD camera
- distance measurement unit
- controller
- signal processor 114:





- 110: CCD camera
- 111: distance measurement unit
- 113: controller
- 114: signal processor
- 117: memory card